# Adaptive optics pre-compensation of laser beams

Szymon Gładysz

Fraunhofer Institute of Optronics, System Technologies and Image Exploitation

Ettlingen, Germany



## Outline

- Pre-compensation of laser beams
- Holographic wavefront sensor (HWFS)
- Possible application in astronomical AO
- Thermal-piezoelectric deformable mirror from Fraunhofer IOF



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## **AO for laser beams**



![](_page_3_Picture_2.jpeg)

## **Related efforts in astronomy**

- Work of Don Gavel et al. (VILLAGES project)
- Correction of static amplitude and phase aberrations of an out-going beam (Pontificia Universidad Catolica de Chile and Gemini Obs.; Bechet et al., Opt Expr, 2014)

![](_page_4_Picture_3.jpeg)

## **Correction of static aberrations (beam shaping)**

From Bechet et al., Opt Expr, 2014:

- Significant distortions of the GeMS laser beam have been observed during the first two years of operation.
- If the LGS spot size is reduced by 15%, it is as if the number of photons had been increased by 40%.
- From the data of April 2013, M<sup>2</sup> factors of 2.21 and 1.21 along x and y directions respectively were found. In October 2013, the corresponding M<sup>2</sup> factors were 2.23 and 1.15.

![](_page_5_Picture_5.jpeg)

## **GeMS beam shapes**

Bechet et al., Opt Expr, 2014

![](_page_6_Figure_2.jpeg)

Fig. 1. Average irradiance map over 20 frames obtained from a  $37 \times 37$  Shack-Hartmann sensor located at the output of the laser, during a run in April 2013 (top) and a run in October 2013 (bottom). Left: Irradiance map, with orthogonal lines of cuts through the maximum. Right: Cuts along x (dashed) and y-axis (solid) of the irradiance map above. The dotted horizontal line marks the half of the maximum.

![](_page_6_Picture_4.jpeg)

## **Two-DM solution**

![](_page_7_Figure_1.jpeg)

Fig. 2. Schematics of 2-DM correcting systems. (a): Mono-static system with DM2 in the far-field of DM1 [20]. The FTM box represents a Fourier transforming mirror. (b): 2-DM correcting system in the near-field proposed in this paper. DM1 is located in the near field of DM2, at a distance *z*. The configuration is named *bistatic* for having different receiving and projecting apertures.

![](_page_7_Picture_3.jpeg)

## **Modified Gerchberg-Saxton algorithm**

![](_page_8_Figure_1.jpeg)

![](_page_8_Picture_2.jpeg)

## **Results of simulations**

![](_page_9_Figure_1.jpeg)

Fig. 3. Amplitudes of the output field at DM2, without correction ((a) and (b)) and with correction ((c) and (d)). Graphics (a) and (c) represent the 2D amplitude over the 1 cm aperture

![](_page_9_Picture_3.jpeg)

## **Results of simulations**

![](_page_10_Figure_1.jpeg)

![](_page_10_Figure_2.jpeg)

![](_page_10_Figure_3.jpeg)

Fig. 6. Phase corrections  $\phi_1$  (left) and  $\phi_2$  (right) to be applied to DM1 and DM2 respectively, after 400 iterations.

![](_page_10_Picture_5.jpeg)

## **Results of experiments**

![](_page_11_Figure_1.jpeg)

![](_page_11_Picture_2.jpeg)

## Outline

### Pre-compensation of laser beams

## Holographic wavefront sensor (HWFS)

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![](_page_12_Picture_5.jpeg)

# Holographic wavefront sensor

(HWFS, Neil et al., 2000; Andersen & Reibel, 2005)

Sensor implementation for one specific wavefront aberration

Hologram recording with

- reference beam = deformed probe beam
- object beam = converging spherical wavefront

![](_page_13_Figure_6.jpeg)

![](_page_13_Picture_7.jpeg)

# Holographic wavefront sensor

Sensor operation for four modes.

![](_page_14_Figure_2.jpeg)

- Measurement of Zernike modes: independent of intensity
- Identification of the amplitude:

$$Signal = |a| \cdot \frac{I_{A_1} - I_{A_2}}{I_{A_1} + I_{A_2}}$$

Playback

Zepp, Gladysz, Stein, J. Adv. Opt. Tech., 2013

![](_page_14_Picture_8.jpeg)

![](_page_15_Figure_1.jpeg)

![](_page_15_Picture_2.jpeg)

![](_page_16_Figure_0.jpeg)

![](_page_16_Picture_1.jpeg)

![](_page_17_Figure_1.jpeg)

![](_page_17_Picture_2.jpeg)

![](_page_18_Figure_1.jpeg)

![](_page_18_Picture_2.jpeg)

![](_page_19_Figure_1.jpeg)

![](_page_19_Picture_2.jpeg)

![](_page_20_Figure_1.jpeg)

![](_page_20_Picture_2.jpeg)

# Optimal design of the holographic wavefront sensor for pre-compensation

![](_page_21_Picture_1.jpeg)

## **DESCRIPTION OF THE PARAMETERS OF THE SIMULATION**

![](_page_22_Figure_1.jpeg)

#### Metric:

Strehl ratio

![](_page_22_Picture_4.jpeg)

![](_page_23_Figure_1.jpeg)

![](_page_23_Picture_2.jpeg)

![](_page_24_Figure_1.jpeg)

![](_page_24_Picture_2.jpeg)

![](_page_25_Figure_1.jpeg)

![](_page_25_Picture_2.jpeg)

![](_page_26_Figure_1.jpeg)

Gain can be as high as 30%.

Azarian & Gladysz, SPIE, 2014

![](_page_26_Picture_4.jpeg)

# Digital holographic wavefront sensor

Implementation for several modes in an optimized geometry

![](_page_27_Figure_2.jpeg)

![](_page_27_Picture_3.jpeg)

![](_page_28_Figure_0.jpeg)

![](_page_28_Picture_1.jpeg)

### Effect of scintillation

![](_page_29_Figure_2.jpeg)

Intensity reduced 90% due to the mask

Marin, Zepp, Gladysz, SPIE, 2014

![](_page_29_Picture_5.jpeg)

## Effect of scintillation

![](_page_30_Figure_2.jpeg)

Changing Scintillation under constant aberration:

Detector radius $(\omega_0)$	2.4	4.0	6.0	7.0	8.0	9.0
Std.dev. $(\lambda)$	0.062	0.054	0.036	0.037	0.038	0.039

- > The variability due to scintillation depends on the detector radius
- > The sensor is insensitive to scintillation

![](_page_30_Picture_7.jpeg)

Effect of beam wander

![](_page_31_Figure_2.jpeg)

![](_page_31_Picture_3.jpeg)

Effect of tip and tilt

![](_page_32_Figure_2.jpeg)

![](_page_32_Picture_3.jpeg)

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- Turbulence effects on laser propagation
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![](_page_33_Picture_6.jpeg)

Lithography: Hologram to blazed grating

![](_page_34_Picture_2.jpeg)

Holographic plate

50% in 1st order

Lithography

![](_page_34_Picture_6.jpeg)

Blazed Grating 95% in 1<sup>st</sup> order Optimized to achieve maximum

diffraction efficiency in a given order

![](_page_34_Picture_9.jpeg)

Optimize diffraction efficiency

![](_page_35_Figure_2.jpeg)

Sequential holographic wavefront sensor

![](_page_35_Picture_4.jpeg)

From modal to zonal wavefront sensor

Zonal recording:

max. pull

![](_page_36_Picture_4.jpeg)

![](_page_36_Picture_5.jpeg)

G. Andersen et.al. (2014) OSA

![](_page_36_Picture_7.jpeg)

From modal to zonal wavefront sensor.

Zonal recording:

max. push

![](_page_37_Picture_4.jpeg)

![](_page_37_Picture_5.jpeg)

From modal to zonal wavefront sensor.

Zonal recording:

max. pull

![](_page_38_Picture_4.jpeg)

![](_page_38_Picture_5.jpeg)

From modal to zonal wavefront sensor.

Zonal recording:

![](_page_39_Picture_3.jpeg)

![](_page_39_Picture_4.jpeg)

Andersen et al. (2014) Opt Expr

![](_page_39_Picture_6.jpeg)

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![](_page_40_Picture_6.jpeg)

## **Unimorph deformable mirrors**

![](_page_41_Figure_1.jpeg)

Application of an electric field (V1) to the piezoceramic between ground and top electrode results in a deformation of the optical surface.

![](_page_41_Picture_3.jpeg)

Standard mirror setup with adhesively bonded piezoelectric layer and glass substrate.

- Single actuator stroke between 1.5 and 3.5µm
- 40 actuators for reproduction of Zernike shapes
- Technology is used for mirrors with 210x210mm aperture and focus-only mirrors

![](_page_42_Picture_4.jpeg)

![](_page_42_Picture_5.jpeg)

Focus-only mirror Mirror diameter: 50mm aperture: 25 mm Stroke: 180µm -> focal length -0.8m @ 800 V supply voltage

![](_page_42_Picture_7.jpeg)

## Thermal piezoelectric deformable mirror

![](_page_43_Picture_1.jpeg)

Thermal piezoelectric deformable mirror with sinter-fused piezoceramic layer and multimaterial substrate.

- 40 actuators for reproduction of Zernike shapes
- Single actuator stroke between 1.5 and 3.5µm
- Additional temperature sensors and actuators
- Mirror shapes beams with 6.2kW on an aperture of 22mm (2kW/cm<sup>2</sup>)

![](_page_43_Picture_7.jpeg)

![](_page_44_Picture_0.jpeg)

Credits: Zepp, Marin, Baena Galle, Barros, Keary, Yatcheva, Hübner, Toselli, Sprung, Wollgarten, Stein

![](_page_44_Picture_2.jpeg)